

# Transformations

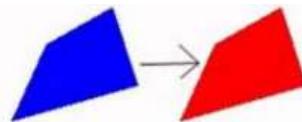
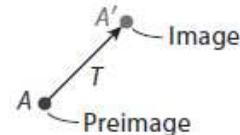
Tuesday, September 25, 2018 7:41 PM

## Transformations

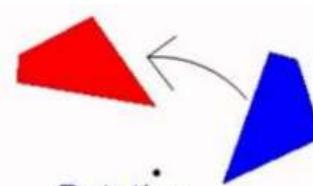
A function that changes the **position, shape, and/or size** of a figure

**Preimage--> Image**

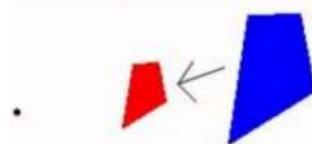
*Use "prime notation"*



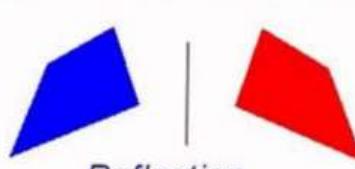
*Translation*



*Rotation*



*Dilation*



*Reflection*

## Rigid Motions

- Rigid motions preserve distance.
- Rigid motions preserve angle measure.
- Rigid motions preserve betweenness.

- Rigid motions preserve collinearity.
- Rigid motions preserve parallelism.

## Translation

Right  $a$  units Add  $a$  to the  $x$ -coordinate:  $(x, y) \rightarrow (x + a, y)$

Left  $a$  units Subtract  $a$  from the  $x$ -coordinate:  $(x, y) \rightarrow (x - a, y)$

Up  $b$  units Add  $b$  to the  $y$ -coordinate:  $(x, y) \rightarrow (x, y + b)$

Down  $b$  units Subtract  $b$  from the  $y$ -coordinate:  $(x, y) \rightarrow (x, y - b)$

## Rotation

Degree	Clockwise	Counterclockwise
$90^\circ$	$(x, y) \rightarrow (y, -x)$	$(x, y) \rightarrow (-y, x)$
$180^\circ$	$(x, y) \rightarrow (-x, -y)$	$(x, y) \rightarrow (-x, y)$
$270^\circ$	$(x, y) \rightarrow (-y, x)$	$(x, y) \rightarrow (y, -x)$
$360^\circ$	$(x, y) \rightarrow (x, y)$	$(x, y) \rightarrow (x, y)$

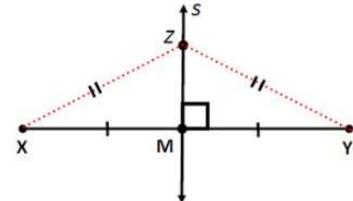
## Reflection

Reflection about the x-axis	(x, y)	(x, -y)
Reflection about the y-axis	(x, y)	(-x, y)
Reflection about the line $y = x$	(x, y)	(y, x)
Reflection about the line $y = -x$	(x, y)	(-y, -x)
Reflection about the origin	(x, y)	(-x, -y)

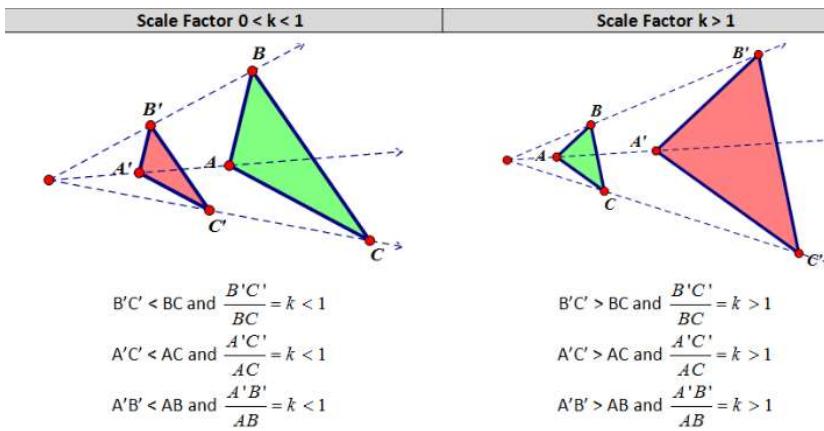
## Perpendicular Bisector

Example:

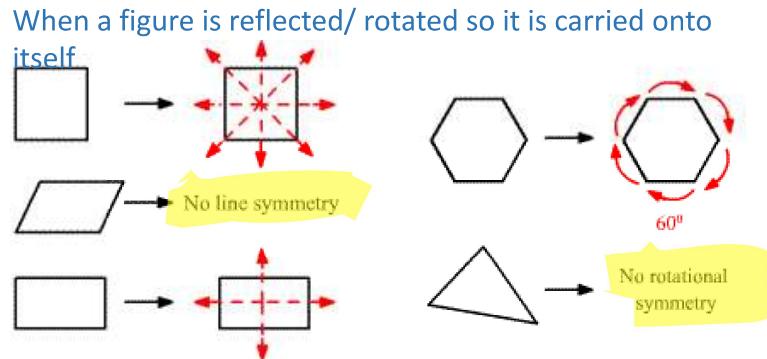
Line  $s$  is perpendicular to  $\overline{XY}$ .  
 M is the midpoint, therefore  $\overline{XM} \cong \overline{MY}$ .  
 Z lies on line  $s$  and is equidistant from X and Y.



## Dilation



## Symmetry



\*\*To find degrees of rotational symmetry, divide 360 by the # of turns